

Two bodies gravitational system with variable mass and damping-anti damping effect due to star wind

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OUTLINE

Comets as an example of variable mass system.

Two body problem and damping-anti damping model.

One degree of freedom equation of motion.

Radial constant of motion, Lagrangian, and Hamiltonian.

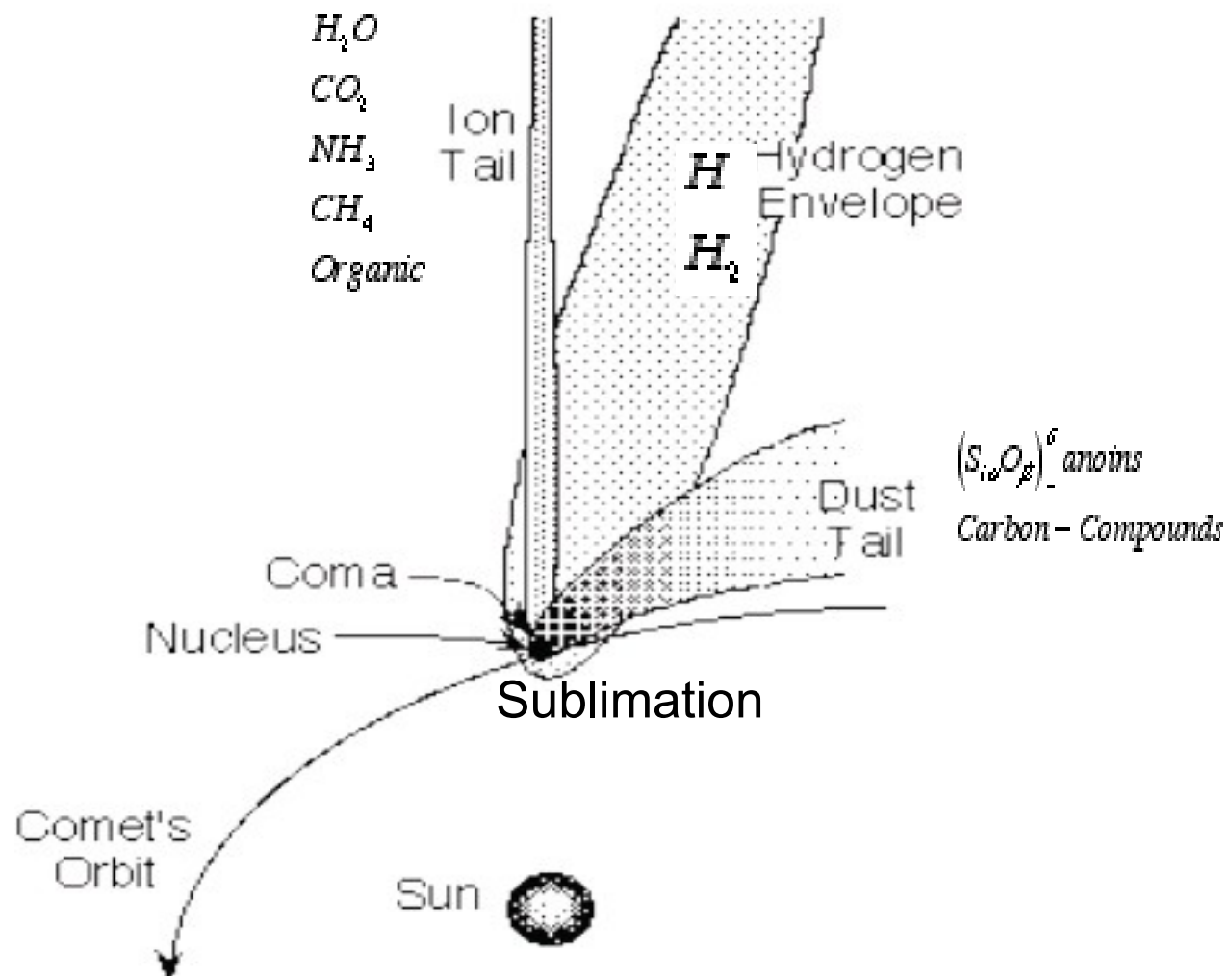
Model for variable mass.


Spiral behavior of the comet and period of motion of motion.

Conclusion.

Comet

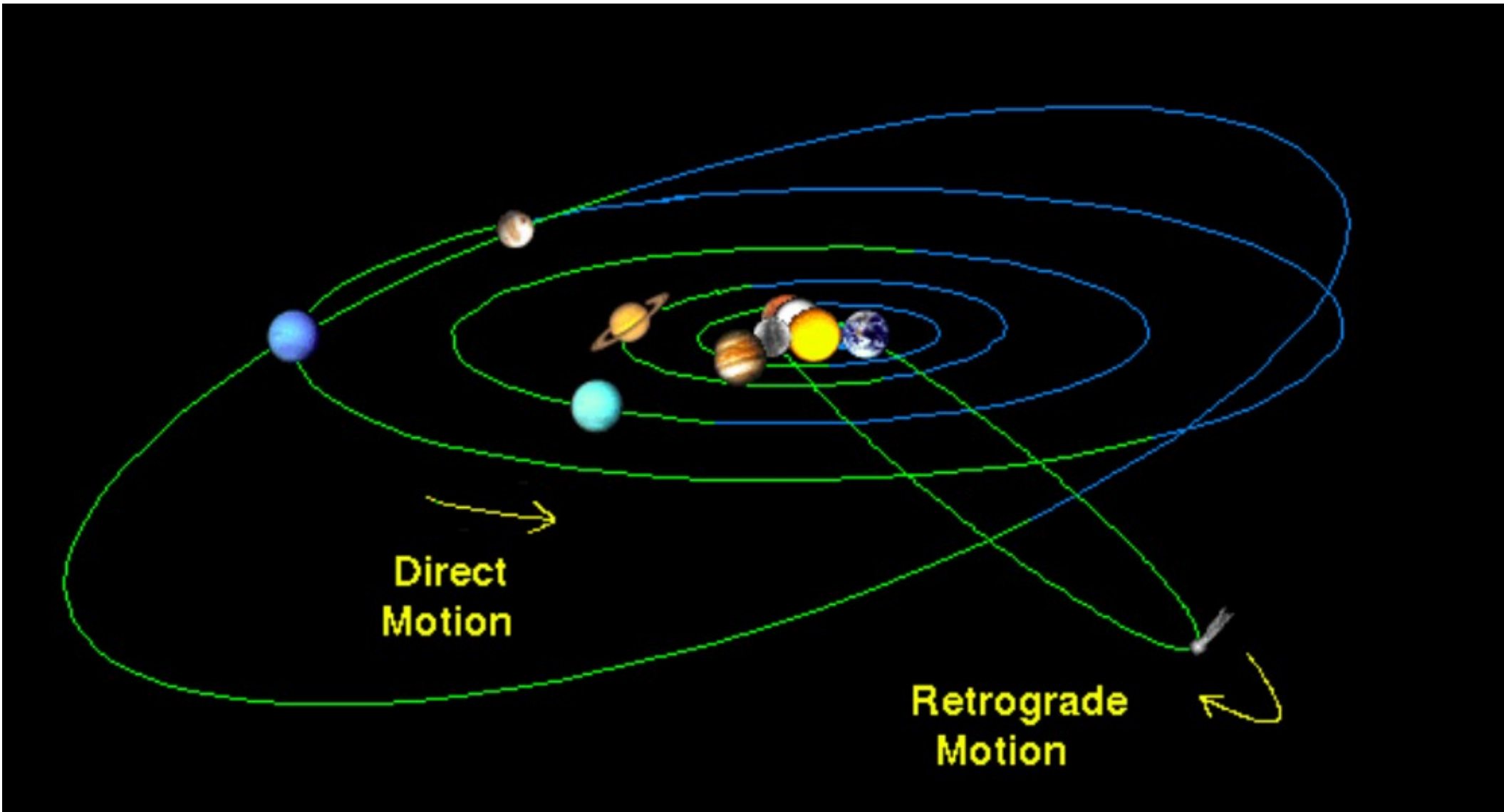
Components Of Comets

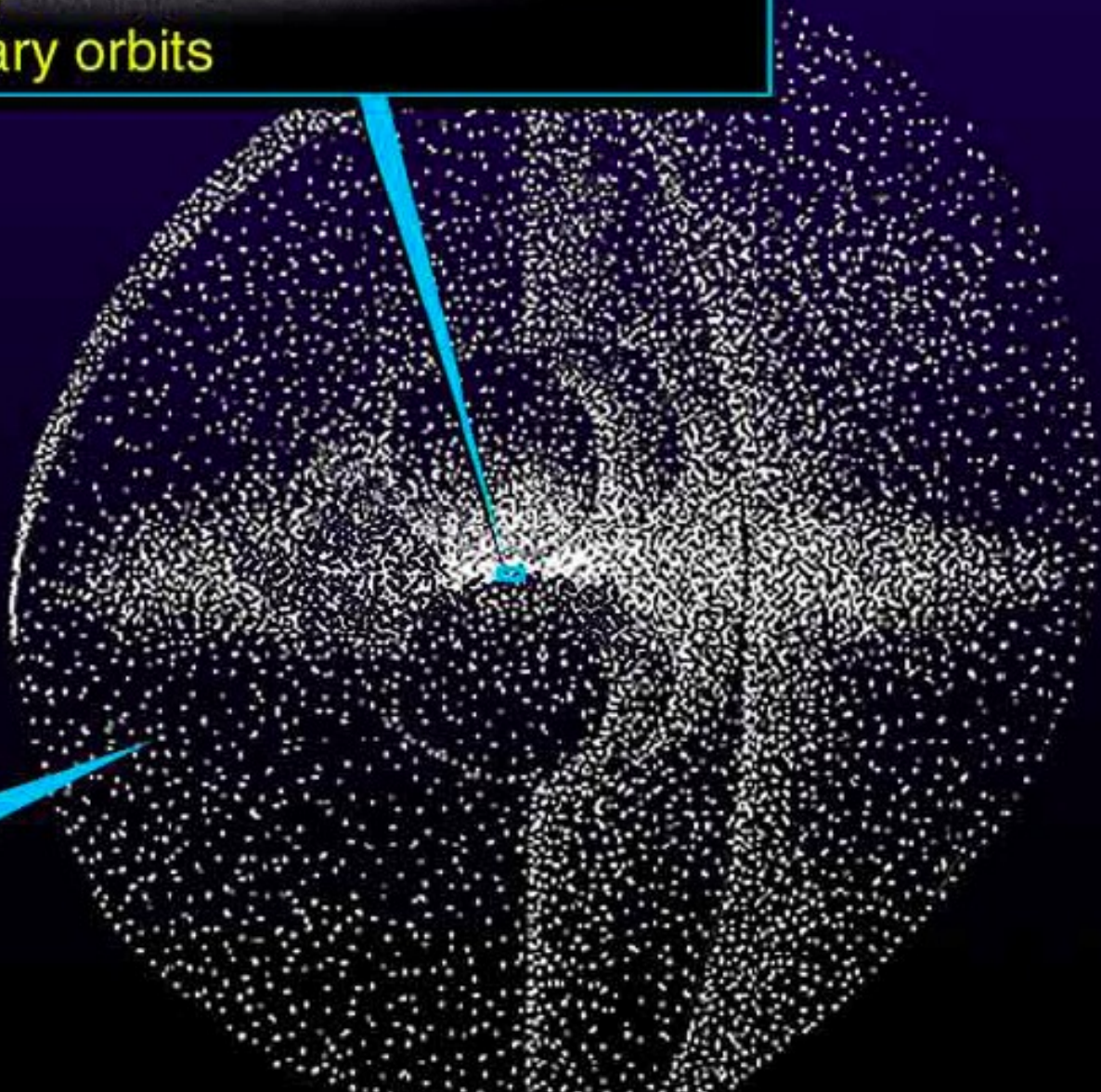
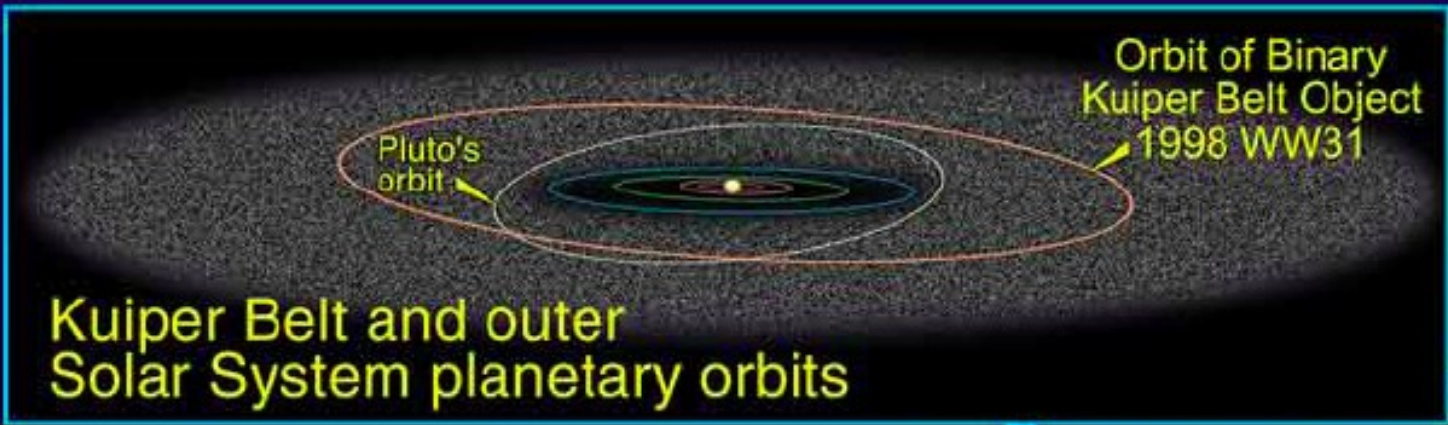




The tail of the
comet always
points away from
the sun

Halley Comet





The Oort Cloud
(comprising many billions of comets)

Oort Cloud cutaway drawing adapted from Donald K. Yeoman's

Equation of Motion

$$\frac{d}{dt} \left(m_1 \frac{d\bar{r}_1}{dt} \right) = - \frac{Gm_1 m_2}{|\bar{r}_1 - \bar{r}_2|^3} (\bar{r}_1 - \bar{r}_2)$$

$$\frac{d}{dt} \left(m_2 \frac{d\bar{r}_2}{dt} \right) = - \frac{Gm_1 m_2}{|\bar{r}_2 - \bar{r}_1|^3} (\bar{r}_2 - \bar{r}_1) - \frac{\gamma}{|\bar{r}_1 - \bar{r}_2|} \left(\frac{d|\bar{r}_1 - \bar{r}_2|}{dt} \right)^2 (\bar{r}_1 - \bar{r}_2)$$

Meshcherski-Gylden (1900) problem

L.M. Berkovich, Celestial Mech. 24 (1981) 407

A.A. Bekov, Astr. Zh. 66 (1989) 135

C Prieto J.A.Docobo, Ast. Ast. 318 (1997) 657

c.m. coordinate system does not help \longrightarrow

Reference system at $\bar{r}_1 = \bar{0}$

$$\bar{r}_2 = \bar{r} = (r \sin \theta \cos \varphi, r \sin \theta \sin \varphi, r \cos \theta)$$

$$m_2 (r - r\dot{\theta}^2 - r\dot{\varphi}^2 \sin^2 \theta) = - \frac{Gm_1 m_2}{r^2} - m_2 r - \gamma r^2$$

$$m_2 (2r\dot{\theta} + r\ddot{\theta} + r\dot{\varphi}^2 \sin \theta \cos \theta) = -m_2 r\dot{\theta}$$

$$m_2 (2r\dot{\varphi} \sin \theta + r\ddot{\varphi} \sin \theta + 2r\dot{\varphi}\dot{\theta} \cos \theta) = -m_2 r\dot{\varphi} \sin \theta \quad \dot{\varphi} = 0$$

$$m_2 (r - r\dot{\theta}^2) = - \frac{Gm_1 m_2}{r^2} - m_2 r - \gamma r^2$$

$$m_2 (2r\dot{\theta} + r\ddot{\theta}) + m_2 r\dot{\theta} = 0. \quad \longrightarrow \quad l_\theta = m_2 r^2 \dot{\theta}$$

$$\ddot{r} = -\frac{Gm_1}{r^2} - \frac{m_2}{m_2} \dot{r} - \frac{\gamma}{m_2} \dot{r}^2 + \frac{l_\theta^2}{m_2^2 r^3}$$

$$m_2 = m_2(r) \quad \longrightarrow \quad m_2 = m'_2 r \quad m' = \frac{dm}{dr}$$

$$\ddot{r} = -\frac{Gm_1}{r^2} - \frac{m'_2 + \gamma}{m_2} \dot{r}^2 + \frac{l_\theta^2}{m_2^2 r^3} \quad \longrightarrow \quad \begin{cases} r = v \\ v = -\frac{Gm_1}{r^2} - \frac{m'_2 + \gamma}{m_2} v^2 + \frac{l_\theta^2}{m_2^2 r^3} \end{cases}$$

$$v \frac{\partial K}{\partial r} + \left[-\frac{Gm_1}{r^2} - \frac{m'_2 + \gamma}{m_2} v^2 + \frac{l_\theta^2}{m_2^2 r^3} \right] \frac{\partial K}{\partial v} = 0 \quad K(r, v) = G(C(r, v))$$

$$C(r, v) = m_2^2 e^{2\gamma(r/v)} v^2 + \int dr \left(\frac{2Gm_1}{r^2} - \frac{2l_\theta^2}{m_2^2 r^3} \right) m_2^2 e^{2\gamma(r/v)} \quad (\text{characteristic curve})$$

$$\Lambda(r) = \int \frac{dr}{m_2(r)}$$

$$\text{By choosing G as: } G_\pm(C) = \frac{C^\pm}{2m_{20}^\pm}$$

$$K^\pm(r, v) = \frac{(m_2^\pm(r))^2 v^2}{2m_{20}^\pm} e^{2\gamma^\pm(r)} + V_{\text{eff}}^\pm(r)$$

$$K^\pm \xrightarrow[\frac{v_1 = \dot{r}}{r=0}]{} E = \frac{1}{2} m_{20} v^2 + V_{\text{eff}}(r)$$

$$V_{\text{eff}}^\pm(r) = \frac{Gm_1}{m_{20}^\pm} \int \frac{(m_2^\pm(r))^2 e^{2\gamma^\pm(r)} dr}{r^2} - \frac{l_\theta^2}{m_{20}^\pm} \int \frac{e^{2\gamma^\pm(r)} dr}{r^2}$$

$$V_{\text{eff}}(r) = -\frac{Gm_1 m_{20}}{r} + \frac{l_\theta^2}{2m_{20} r^2}$$

It has an minimum at $r^* \left(\frac{d^2 V_{\text{eff}}^\pm}{dr^2} \right)_{r=r^*} > 0$

$$r^* (m_2(r^*))^2 = \frac{l_\theta^2}{Gm_1}$$

$$L^\pm = v^2 \int \frac{K^\pm(r, v) dv}{v^2} \quad P^\pm = \frac{\partial L^\pm}{\partial v}$$

$$H^\pm = vp^\pm - L^\pm$$

$$L^\pm = \frac{(m_2^\pm(r))^2 v^2}{2m_{20}^\pm} e^{2\gamma^\pm(r)} - V_{\text{eff}}^\pm(r)$$

$$p = \frac{(m_2^\pm(r))^2 e^{2\gamma^\pm(r)}}{m_{20}^\pm} v$$

$$H^\pm = \frac{m_{20}^\pm P^{\pm 2}}{2(m_2^\pm(r))^2} e^{-2\gamma^\pm(r)} + V_{\text{eff}}^\pm(r)$$

- G.Darboux, (1986)
- E.T. Whittaker, (1917)
- J.Douglas, Amer. Math. Soc.,50 (1941) 71.
- J.A. Kobussen, Acta Phys Austriaca, 51, (1979) 293.
- C. Leubner, Physica A, 86 (1981) 2.
- G.López, Ann. Phys. 251 (1996) 383.
- G. López, Int. J. Theo. Phys. (2008)

$$v = (\pm)e^{-\gamma \delta^{\pm} / r} \sqrt{\frac{2m_{20}^{\pm}}{(m_2^{\pm}(r))^2} [K_0^{\pm} - V_{eff}^{\pm}(r)]^{1/2}}$$

$$p = (\pm)e^{+\gamma \delta^{\pm} / r} \sqrt{\frac{2(m_2^{\pm}(r))^2 m_{20}^{\pm}}{m_{20}^{\pm}} [H_0^{\pm} - V_{eff}^{\pm}(r)]^{1/2}}$$

Mass lost model

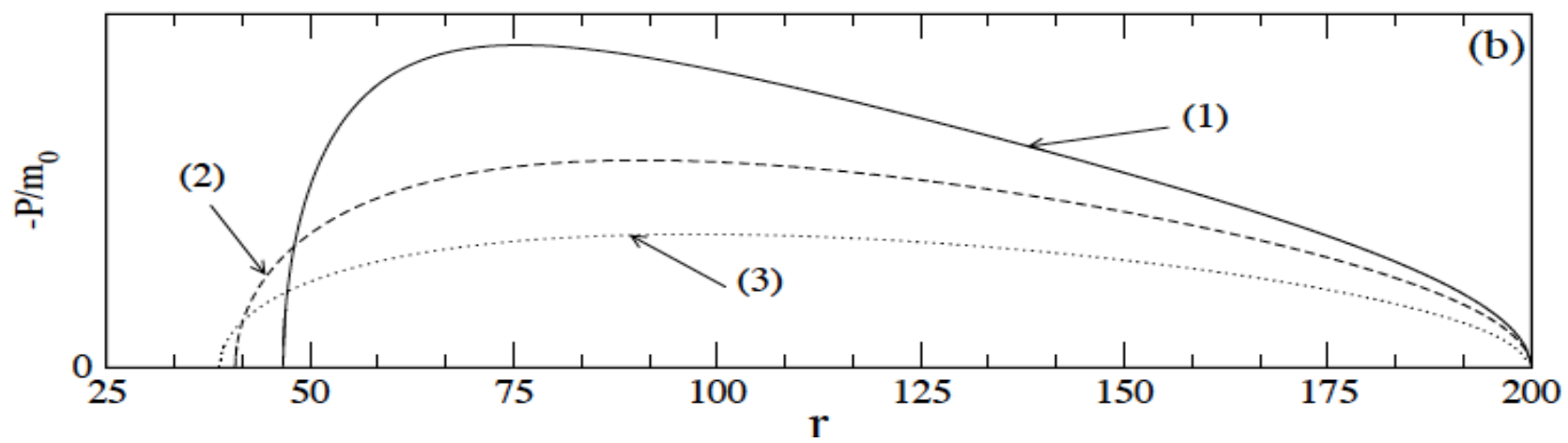
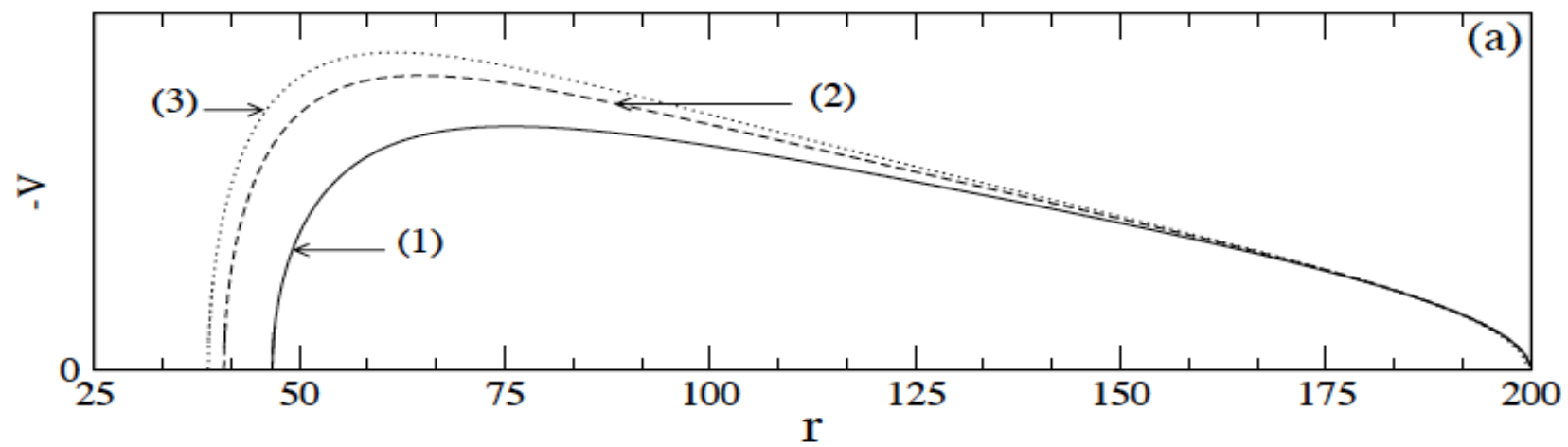
$$m_2^{\pm}(r) = \begin{cases} m_2^-(r_a)(1 - e^{-\alpha r}) \dots\dots\dots (+) v < 0 & \alpha = \alpha(\delta m) \\ m_2^+(r_p) - b(1 - e^{-\alpha(r-r_p)}) \dots\dots (-) v > 0 & b = b(\delta m) \end{cases}$$

$$\Lambda^+(r) = \frac{1}{\alpha m_a} \ln(e^{\alpha r} - 1)$$

$$\Lambda^-(r) = \frac{-1}{\alpha(b - m_p)} \left[\alpha r + \ln(m_p - b(1 - e^{-\alpha(r-r_p)})) \right]$$

$$V_{eff}^+(r) = \left[-\frac{Gm_1 m_2}{r} + \frac{l_{\theta}^2}{2m_2 r^2} \right] e^{2\gamma r / m_a} + W_1(\gamma, \alpha, r)$$

$$V_{eff}^-(r) = \left[-\frac{Gm_1 m_2}{r} + \frac{l_{\theta}^2}{2m_2 r^2} \right] \frac{e^{2\gamma r / (m_p - b)}}{(m_p - b)e^{2\gamma r / (m_p - b)}} + W_2(\gamma, \alpha, r)$$



$$m_s \approx 1.9891 \times 10^{30} \text{ Kg}$$

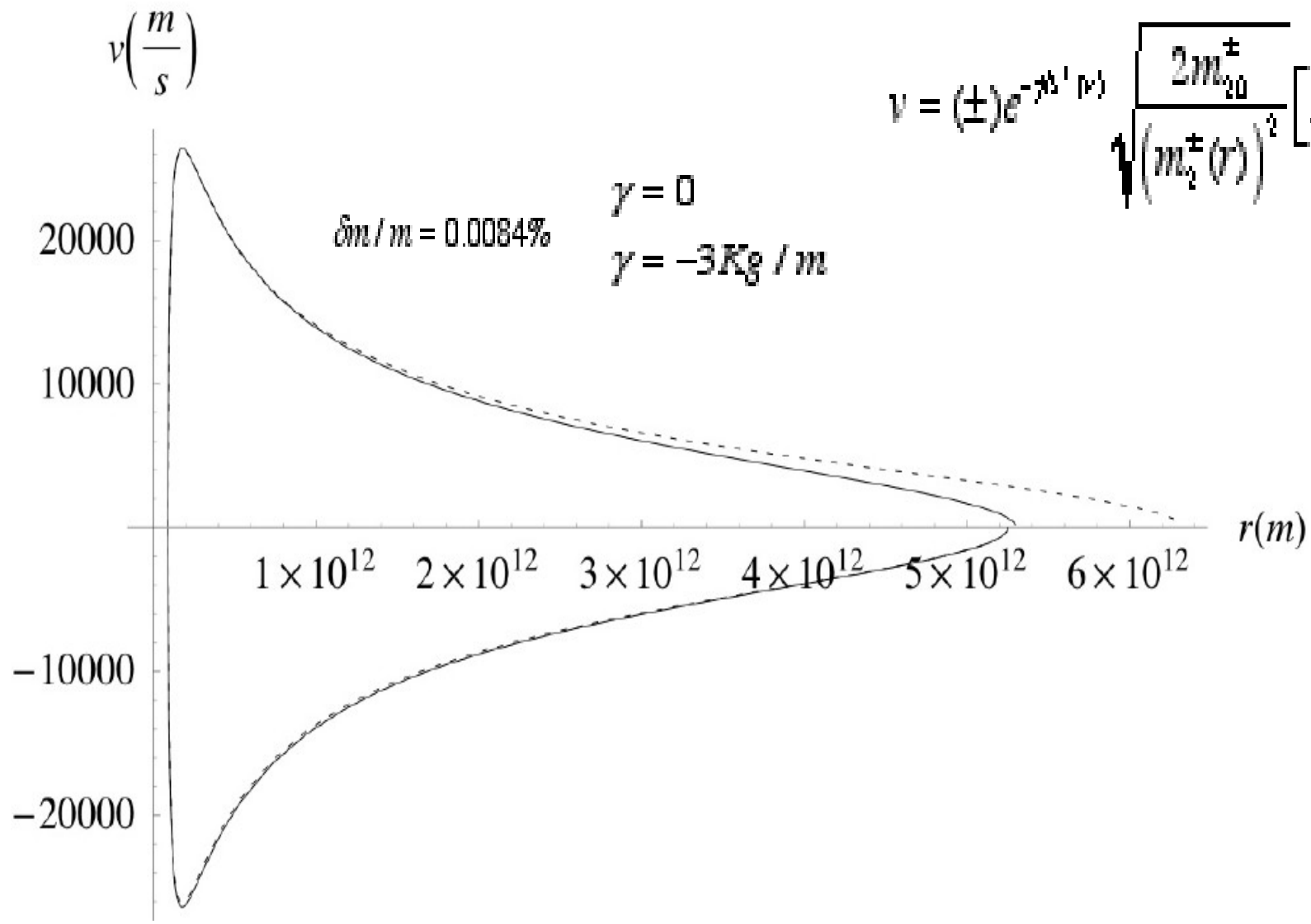
$$m_c \approx 2.3 \times 10^{14} \text{ Kg}$$

$$r_p \approx 0.6 \text{ au}$$

$$r_a \approx 35 \text{ au}$$

$$l_e \approx 10.83 \times 10^{29} \text{ Kg.m}^2 / \text{s}$$

$$\text{au} = 149597870.7 \text{ km}$$

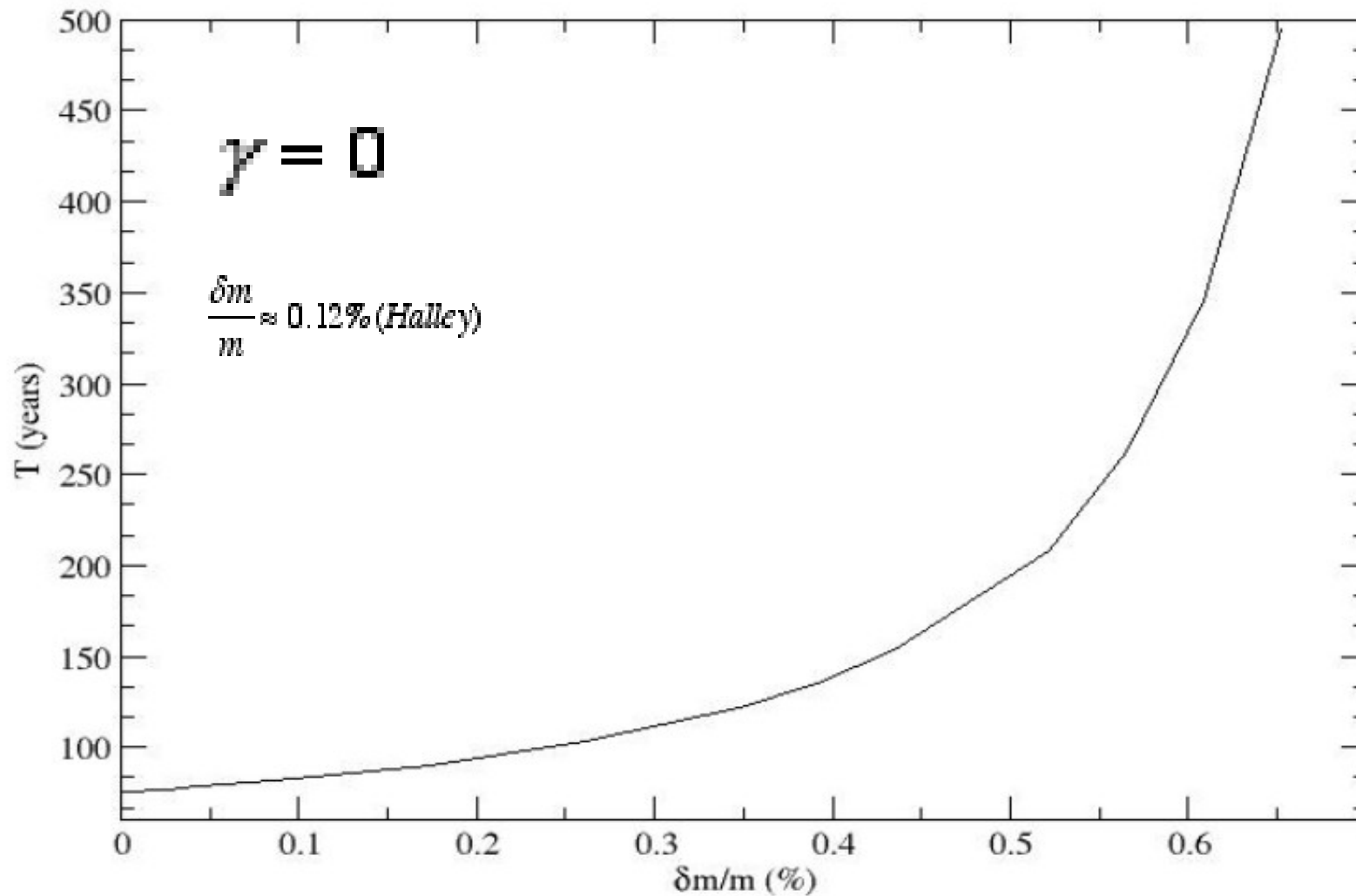


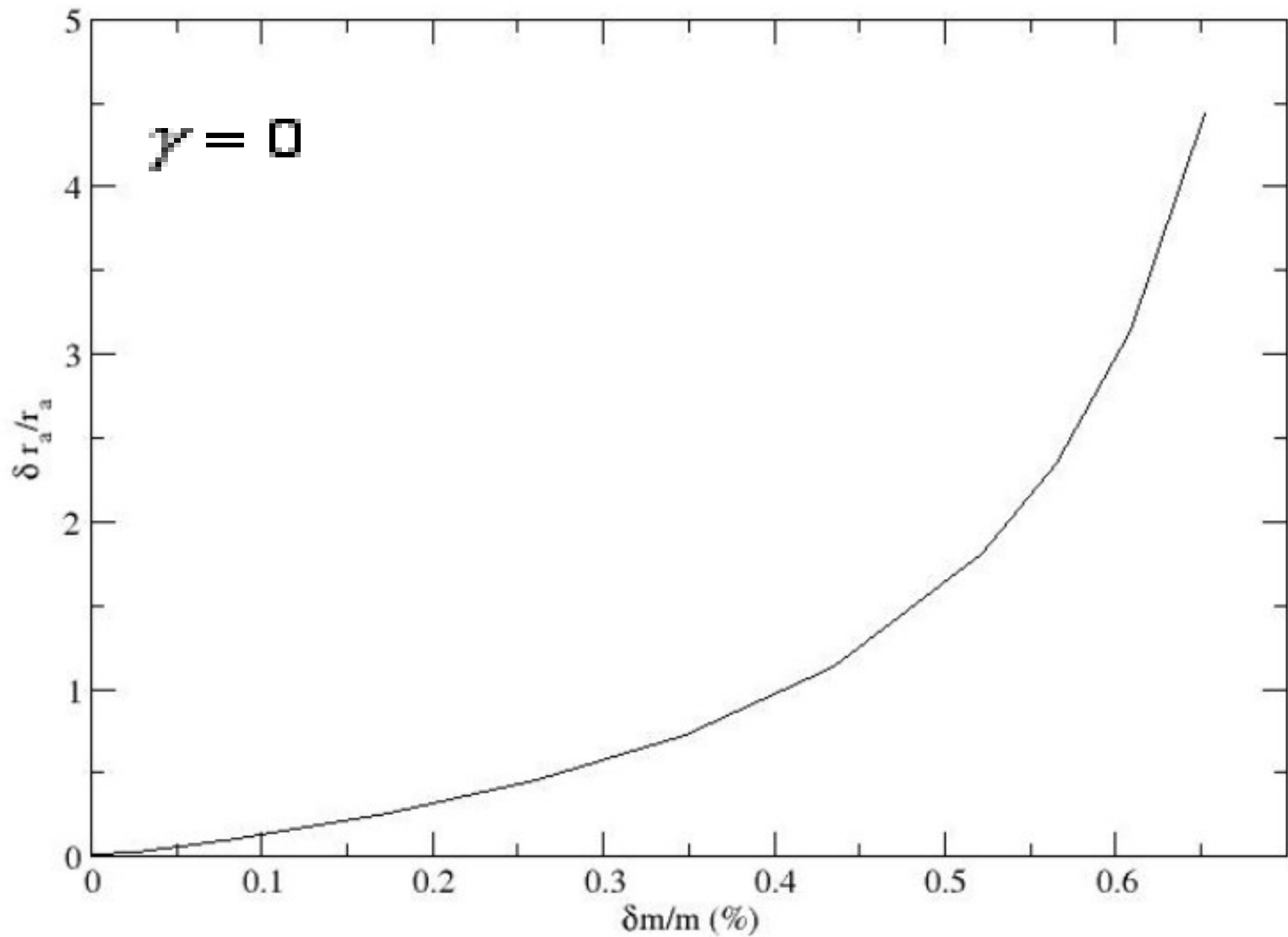
$$v = (\pm) e^{-\gamma r / v} \sqrt{\frac{2m_{c0}^{\pm}}{(m_c^{\pm}(r))^2} [K_0^{\pm} - V_{cf}^{\pm}(r)]^{1/2}}$$

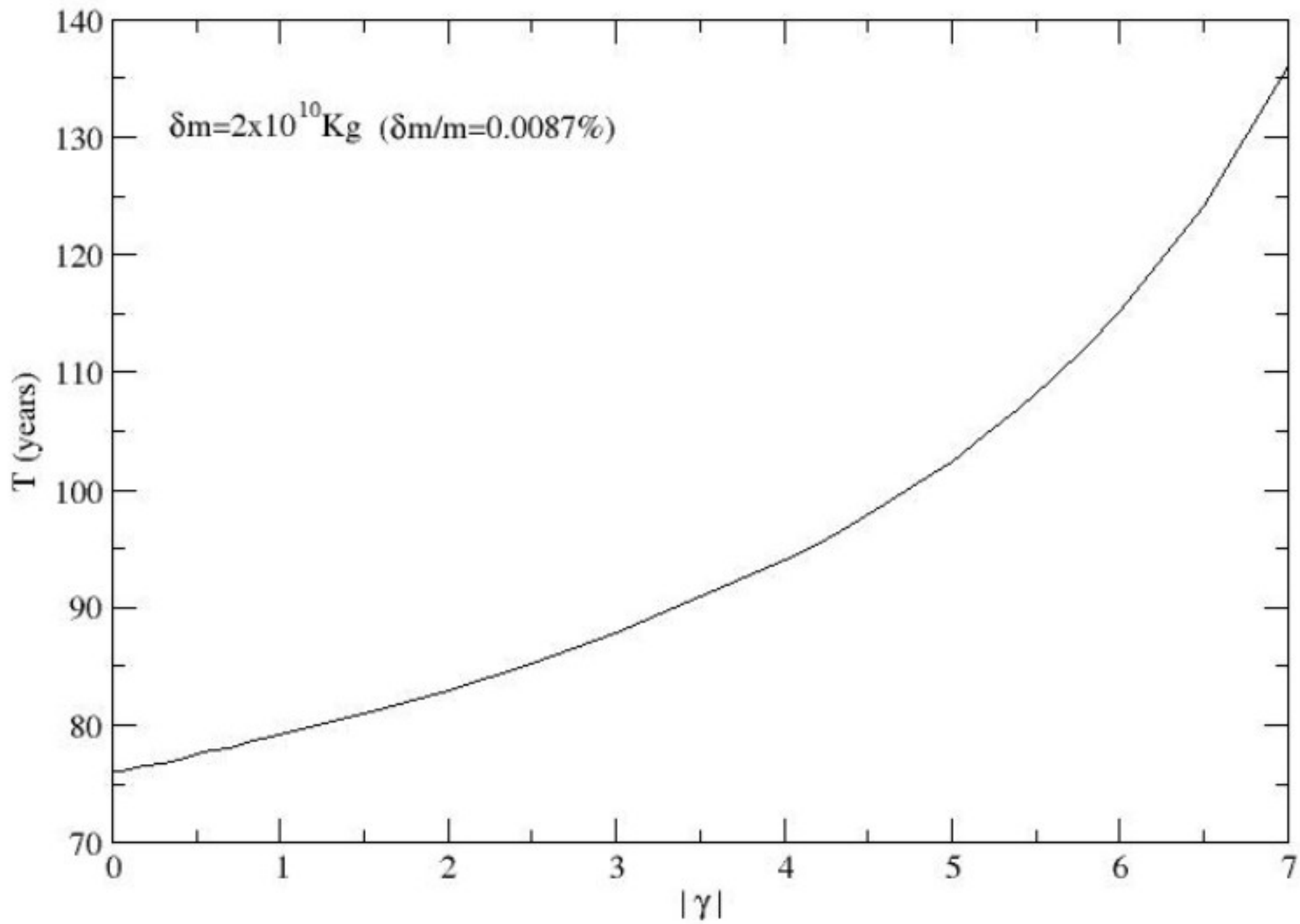
period:

$$T_{1/2}^{\pm} = \frac{1}{\sqrt{2m_{\text{eff}}^{\pm}}} \int_{r_p}^{r_a} \frac{m_2^{\pm}(r) e^{\gamma \ln^2(r)} dr}{\sqrt{K_0^{\pm} - V_{\text{eff}}^{\pm}(r)}}$$

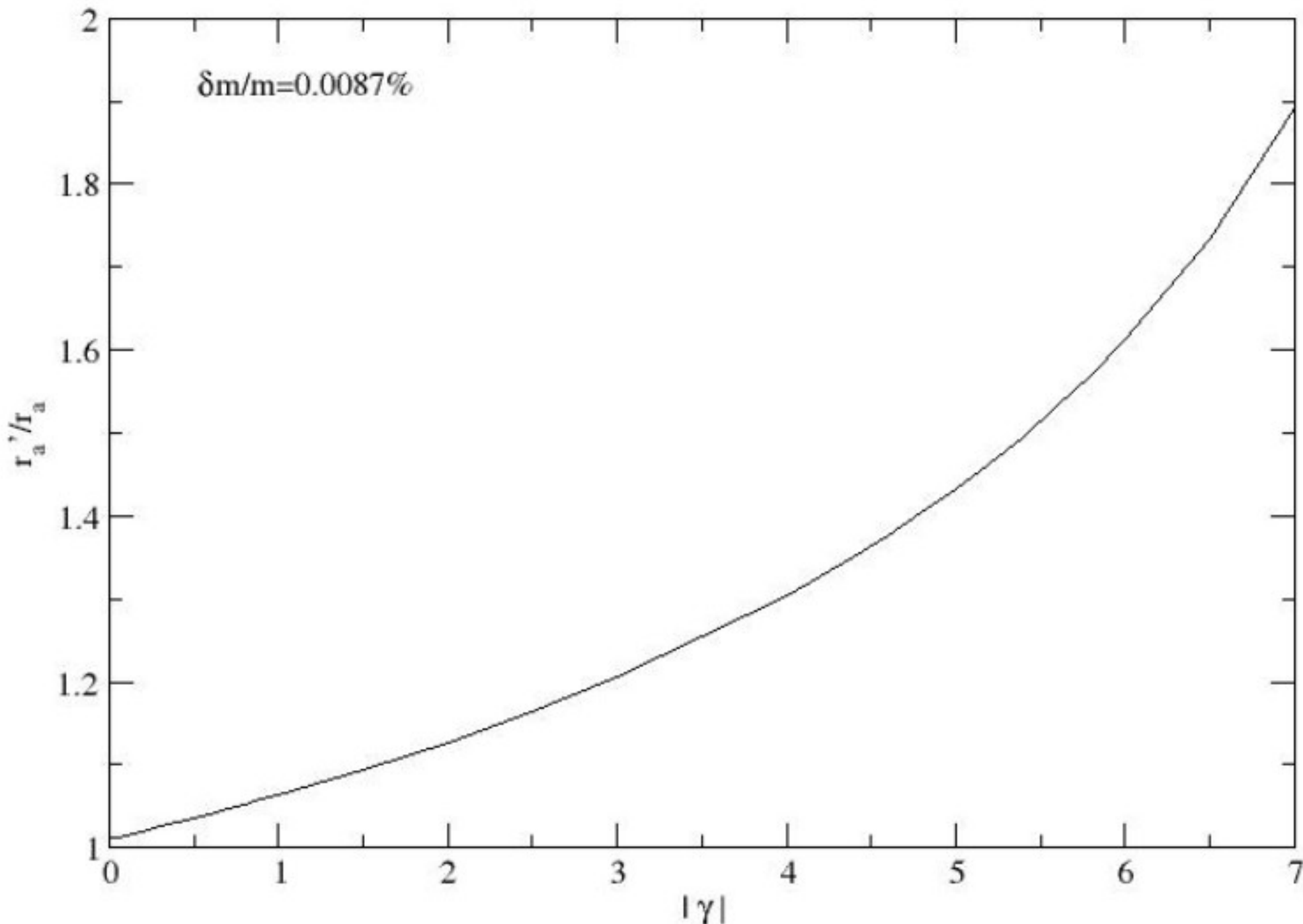
$$T = T_{1/2}^{-} + T_{1/2}^{+}$$







$\delta m/m = 0.0087\%$



Conclusions:

Taking the reference system in the body of fixed mass, the two 3-D gravitational bodies problem is reduced a 1-D equation. Then, a constant of motion, a Lagrangian and a Hamiltonian are obtained for the radial part of the motion.

A model for the mass variation is given, and the resulting trajectories in the (r,v) space (constant of motion) are different from those in the (r,p) space (Hamiltonian).

Orbits of the comet are not close neither ellipticals but spiral out as the mass of the comet lost . The period of the comet increases with the comet mass lost.

Damping-anti damping force makes the comet to move away even more from the star, increasing the aphelion, perihelion distances and the period of the comet.